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Part 1 - Linear

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1.2. Linear Programming: A Graphical Perspective
in R2 13 The feasible region is shown in Figure 1.4. The LP has alternative optimal solutions that fall on the segment connecting $x = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ to $x = \begin{pmatrix} 6 \\ 0 \end{pmatrix}$. Each such solution has an objective value of $z =$

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12, and the
parametric
representation of the
segment is given by x
 $= \begin{bmatrix} 3t+6(1-t) \\ t+0(1-t) \end{bmatrix}$...

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Manual - separate parts Part I is a self-contained introduction to linear

programming, a key component of optimization theory

The presentation in this part is fairly conventional, covering the main elements of the underlying theory of linear programming,

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